

## On Hyper Generalized Quasi Einstein Manifolds

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**Abstract:** In this paper its proved three theorems about global properties of hyper generalized quasi-Einstein manifolds.

**Key Words:** Non-flat Riemannian manifold, hyper generalized quasi Einstein manifold  $(HGQE)_n$ , compact orientable.

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### §1. Introduction

The notion of quasi Einstein manifold was introduced in a paper [8] by M.C.Chaki and R.K.Maity. According to them a non-flat Riemannian manifold  $(M^n, g), (n \geq 3)$  is defined to be a quasi Einstein manifold if its Ricci tensor  $S$  of type  $(0, 2)$  satisfies the condition

$$S(X, Y) = ag(X, Y) + bA(X)A(Y) \quad (1)$$

and is not identically zero, where  $a, b$  are scalars  $b \neq 0$  and  $A$  is a non-zero 1-form such that

$$g(X, \xi_1) = A(X), \quad \forall X \in TM, \quad (2)$$

where,  $\xi_1$  is a unit vector field.

In such a case  $a, b$  are called the associated scalars.  $A$  is called the associated 1-form. Such an  $n$ -dimensional manifold is denoted by the symbol  $(QE)_n$ .

Again, U.C.De and G.C.Ghosh defined generalized quasi Einstein manifold. A non-flat Riemannian manifold is called a generalized quasi Einstein manifold if its Ricci-tensor  $S$  of type  $(0, 2)$  is non-zero and satisfies the condition

$$S(X, Y) = ag(X, Y) + bA(X)A(Y) + cB(X)B(Y), \quad (3)$$

where  $a, b, c$  are non-zero scalars and  $A, B$  are two 1-forms such that

$$g(X, \xi_1) = A(X) \quad \text{and} \quad g(X, \xi_2) = B(X) \quad (4)$$

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with  $\xi_1, \xi_2$  unit vectors which are orthogonal, i.e.,

$$g(\xi_1, \xi_2) = 0. \quad (5)$$

This type of manifold are denoted by  $G(QE)_n$ .

In [16], H.G. Nagaraja introduced the concept of  $N(k)$ -mixed quasi Einstein manifold and mixed quasi constant curvature. A non flat Riemannian manifold  $(M^n, g)$  is called a  $N(k)$ -mixed quasi Einstein manifold if its Ricci tensor of type  $(0, 2)$  is non zero and satisfies the condition

$$S(X, Y) = ag(X, Y) + bA(X)B(Y) + cB(X)A(Y), \quad (6)$$

where  $a, b, c$  are smooth functions and  $A, B$  are non zero 1-forms such that

$$g(X, \xi_1) = A(X) \quad \text{and} \quad g(X, \xi_2) = B(X) \quad \forall \quad X, \quad (7)$$

with  $\xi_1, \xi_2$  the orthogonal unit vector fields. Such manifold is denoted by the symbol  $N(k) - (MQE)_n$ .

The notion of hyper-generalized quasi Einstein manifold has been introduced by A.A.Shaikh, C. Özgür and A.Patra[17] in 2011. An  $n$ -dimensional Riemannian manifold  $(M^n, g)$  ( $n > 2$ ) is called a hyper generalized quasi-Einstein manifold if its Ricci tensor of type  $(0, 2)$  is non zero and satisfies the following condition

$$\begin{aligned} S(X, Y) = & ag(X, Y) + bA(X)A(Y) + c[A(X)B(Y) + A(Y)B(X)] \\ & + d[A(X)D(Y) + A(Y)D(X)] \end{aligned} \quad (8)$$

for all  $X, Y \in \chi(M)$ , where  $a, b, c$  and  $d$  are real valued, non-zero scalars functions on  $(M^n, g)$ .  $A, B$  and  $D$  are non zero 1-forms such that

$$g(X, \xi_1) = A(X), \quad g(X, \xi_2) = B(X) \quad \text{and} \quad g(X, \xi_3) = D(X), \quad (9)$$

where  $\xi_1, \xi_2, \xi_3$  are three unit vector fields mutually orthogonal to each other at every point on  $M$ . Here  $a, b, c, d$  are called the associated scalars,  $A, B, D$  are called the associated main and auxiliary 1-forms. We denote this type of manifold  $(HGQE)_n$ .

## §2. Preliminaries

From (8) and (9), we get

$$S(X, X) = a|X|^2 + b|g(X, \xi_1)|^2 + 2c|g(X, \xi_1)g(X, \xi_2)| + 2d|g(X, \xi_1)g(X, \xi_3)|, \quad \forall \quad X. \quad (10)$$

Let  $\theta_1$  be the angle between  $\xi_1$  and any vector  $X$ ;  $\theta_2$  be the angle between  $\xi_2$  and any

vector  $X$ ;  $\theta_3$  be the angle between  $\xi_3$  and any vector  $X$ . Then

$$\cos \theta_1 = \frac{g(X, \xi_1)}{\sqrt{g(\xi_1, \xi_1)}\sqrt{g(X, X)}} = \frac{g(X, \xi_1)}{\sqrt{g(X, X)}}$$

as  $g(\xi_1, \xi_1) = 1$ , and

$$\cos \theta_2 = \frac{g(X, \xi_2)}{\sqrt{g(X, X)}} \quad \text{and} \quad \cos \theta_3 = \frac{g(X, \xi_3)}{\sqrt{g(X, X)}}.$$

If  $b > 0$ ,  $c > 0$ , we have from (10)

$$\begin{aligned} (a + b + 2c + 2d)|X|^2 &\geq a|X|^2 + b|g(X, \xi_1)|^2 + 2c|g(X, \xi_1)g(X, \xi_2)| \\ &\quad + 2d|g(X, \xi_1)g(X, \xi_3)| = S(X, X). \end{aligned} \quad (11)$$

Now, contracting (8) over  $X$  and  $Y$ , we get

$$r = na, \quad (12)$$

where  $r$  is the scalar curvature. Since  $\xi_1, \xi_2$  and  $\xi_3$  are orthogonal unit vector fields, therefore  $g(\xi_1, \xi_1) = 1$ ,  $g(\xi_2, \xi_2) = 1$ ,  $g(\xi_3, \xi_3) = 1$ ,  $g(\xi_1, \xi_2) = 0$ ,  $g(\xi_1, \xi_3) = 0$  and  $g(\xi_2, \xi_3) = 0$ .

Again, putting  $X = Y = \xi_1$  in (8) we get  $S(\xi_1, \xi_1) = a + b$ . Putting  $X = Y = \xi_2$  in (8) we get  $S(\xi_2, \xi_2) = a$ . Putting  $X = Y = \xi_3$  in (8) we get  $S(\xi_3, \xi_3) = a$ .

If  $X$  is a unit vector field, then  $S(X, X)$  is the Ricci-curvature in the direction of  $X$ .

Notice that  $Q$  is the symmetric endomorphism of the tangent space at each point corresponding to the Ricci-tensor  $S$ , where

$$g(QX, Y) = S(X, Y) \quad \forall X, Y \in TM. \quad (13)$$

Let  $l^2$  denote the squares of the lengths of the Ricci-tensor  $S$ . Then

$$l^2 = \sum_{i=1}^n S(Qe_i, e_i), \quad (14)$$

where  $\{e_i\}$ ,  $i = 1, 2, \dots, n$  is an orthonormal basis of the tangent space at a point of  $(HGQE)_n$ .

Now from (8) we get

$$\begin{aligned} S(Qe_i, e_i) &= ag(Qe_i, e_i) + bA(Qe_i)A(e_i) + c[A(Qe_i)B(e_i) + A(e_i)B(Qe_i)] \\ &\quad + d[A(Qe_i)D(e_i) + A(e_i)D(Qe_i)], \end{aligned}$$

i.e.,

$$l^2 = (n - 2)a^2 + (a + b)^2 + 2c^2 + 2d^2. \quad (15)$$

These result will be used in the sequel.

### §3. Ricci Semi-symmetric $(HGQE)_n (n > 3)$

Chaki and Maity proved that  $(QE)_n (n > 3)$  is Ricci Semi-symmetric if and only if

$$A(R(X, Y)Z) = 0.$$

Let us suppose that  $(HGQE)_n (n > 3)$  is Ricci-Semi symmetric. Then

$$A(R(X, Y)Z) = 0. \quad (16)$$

From (16) we get

$$A(Q(X)) = 0, \quad (17)$$

where  $Q$  be the symmetric endomorphism of the tangent space at each point corresponding to the Ricci tensor  $S$ . Then

$$g(QX, Y) = S(X, Y). \quad (18)$$

Then from (8) we get

$$A(Q(X)) = (a + b)A(X) + cB(X) + dD(X). \quad (19)$$

From (17) and (19) it follows that

$$(a + b)A(X) + cB(X) + dD(X) = 0. \quad (20)$$

Thus we can state the following.

**Theorem 3.1** *If a  $(HGQE)_n$  is Ricci Semi symmetric than  $(a+b)A(X)+cB(X)+dD(X)=0$ .*

### §4. Sufficient Condition for a Compact Orientable $(HGQE)_n (n \geq 3)$ Without Boundary to be Isometric to a Sphere

In this section we consider a compact, orientable  $(HGQE)_n$  without boundary having constant associated scalars  $a, b, c$  and  $d$ . Then from (11) and (15), it follows that the scalar curvature is constant and so also is the length of the Ricci-tensor.

We further suppose that  $(HGQE)_n$  under consideration admits a non-isometric conformal motion generated by a vector field  $X$ . Since  $l^2$  is constant, it follows that

$$\mathcal{L}_X l^2 = 0, \quad (21)$$

where  $\mathcal{L}_X$  denotes Lie differentiation with respect to  $X$ .

Now, it is known ([2], [4], [5], [9], [12], [13], [14], [15]) that if a compact Riemannian manifold  $M$  of dimension  $n > 2$  with constant scalar curvature admits an infinitesimal non-isometric conformal transformation  $X$  such that  $\mathcal{L}_X l^2 = 0$  then  $M$  is isometric to a sphere. But a sphere is Einstein so that  $b, c$  and  $d$  vanish which is a contradiction. This leads to the following theorem.

**Theorem 4.1** *A compact orientable hyper generalized quasi Einstein manifold  $(HGQE)_n$  ( $n \geq 3$ ) without boundary does not admit a non-isometric conformal vector field.*

### §5. Killing Vector Field in a Compact Orientable $(HGQE)_n$ ( $n \geq 3$ ) Without Boundary

In this section, we consider a compact, orientable  $(HGQE)_n$  ( $n \geq 3$ ) without boundary with  $a, b, c$  and  $d$  as associated scalars.

It is known [4] that in such a manifold  $M$ , the following relation holds

$$\int_M [S(X, X) - |\nabla X|^2 - (\operatorname{div} X)^2] dv \leq 0 \quad \forall X. \quad (22)$$

If  $X$  is a killing vector field, then  $\operatorname{div} X = 0$  ([4]). Hence (22) takes the form

$$\int_M [S(X, X) - |\nabla X|^2] dv = 0. \quad (23)$$

Let  $b > 0, c > 0, d > 0$ . Then by (11)

$$(a + b + 2c + 2d)|X|^2 \geq S(X, X). \quad (24)$$

Therefore,

$$(a + b + 2c + 2d)|X|^2 - |\nabla X|^2 \geq S(X, X) - |\nabla X|^2. \quad (25)$$

Consequently,

$$\int_M [(a + b + 2c + 2d)|X|^2 - |\nabla X|^2] dv \geq \int_M [S(X, X) - |\nabla X|^2] dv, \quad (26)$$

and by (23)

$$\int_M [(a + b + 2c + 2d)|X|^2 - |\nabla X|^2] dv \geq 0. \quad (27)$$

If  $a + b + 2c + 2d < 0$ , then

$$\int_M [(a + b + 2c + 2d)|X|^2 - |\nabla X|^2] dv = 0. \quad (28)$$

Therefore,  $X = 0$ . This leads to the following.

**Theorem 5.1** *If in a compact orientable  $(HGQE)_n$  ( $n \geq 3$ ) without boundary and the associated scalars are such that  $b > 0, c > 0, d > 0$  and  $a + b + 2c + 2d < 0$ , then there exists no non-zero killing vector field in this manifold.*

**Corollary 5.1** *If in a compact orientable  $(HGQE)_n$  ( $n \geq 3$ ) without boundary, and each of the associated scalars  $a, b, c, d$ , is greater than zero, then any harmonic vector field  $X$  in the  $(HGQE)_n$  is parallel and orthogonal to one of the generators of the manifold which makes greatest angle with the vector  $X$ .*

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