

## On $M$ -Projective Curvature Tensor of a $(LCS)_n$ -Manifold

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**Abstract:** In the present paper, we characterize the  $M$ -projective curvature tensor in a  $(LCS)_n$ -manifold. Geometric properties on the curvature tensor such as  $\phi$ - $M$ -projective flat,  $M$ -projective pseudosymmetric,  $\phi$ - $M$ -projective semisymmetric and generalized  $M$ -projective  $\phi$ -recurrent are studied on  $(LCS)_n$ -manifold.

**Key Words:**  $(LCS)_n$ -Manifold,  $M$ -projective curvature tensor,  $\phi$ - $M$ -projective semisymmetric,  $\phi$ - $M$ -projective flat, generalized  $M$ -projective  $\phi$ -recurrent,  $M$ -projective pseudosymmetric.

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### §1. Introduction

In 2003, Shaikh [18] introduced and studied Lorentzian concircular structure manifolds (briefly  $(LCS)_n$ -manifolds) with an example, which generalizes the notion of LP-Sasakian manifolds introduced by Matsumoto [11]. Also Shaikh et al. ([19,20,21,22]), Prakasha [16], Yadav [29] studied various types of  $(LCS)_n$ -manifolds by imposing curvature restrictions.

In 1926, the concept of local symmetry of a Riemannian manifold was started by Cartan [3]. This notion has been used in several directions by many authors such as recurrent manifolds by Walker [28], semi-symmetric manifold by Szabo [24], pseudosymmetric manifold by Chaki [4], pseudosymmetric spaces by Deszcz [10], weakly symmetric manifold by Tamassy and Binh [26], weakly symmetric Riemannian spaces by Selberg [17]. The notions of pseudo-symmetric and weak symmetry by Chaki and Deszcz and Selberge and Tamassy and Binh respectively are different. As a mild version of local symmetry, Takahashi [25] introduced the notion of  $\phi$ -symmetry on a Sasakian manifold. In 2003, De et al. [7] introduced the concept of  $\phi$ -recurrent Sasakian manifold, which generalizes the notion of  $\phi$ -symmetry.

In 1971, Pokhariyal and Mishra [15] defined a tensor field  $W^*$  on a Riemannian manifold given by

$$\begin{aligned} W^*(X, Y)Z &= R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, Z)X - S(X, Z)Y + g(Y, Z)QX \\ &\quad - g(X, Z)QY]. \end{aligned} \quad (1.1)$$

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Such a tensor field  $W^*$  is known as  $M$ -projective curvature tensor. Ojha [13,14] studied  $M$ -projective curvature tensor on Sasakian and Kaehler manifold. The properties of  $M$ -projective curvature tensor were also studied on different manifolds by Chaubey [5,6], Venkatesha [27] and others.

Motivated by the above studies, we made an attempt to study  $M$ -projective curvature tensor on  $(LCS)_n$ -manifold.

The present paper is organized as follows: Section 2 is equipped with some preliminaries of  $(LCS)_n$  manifold. In section 3, we proved that if  $(M^n, g)$  is an  $n$ -dimensional  $\phi$ - $M$ -projective flat  $(LCS)_n$ -manifold, then the manifold  $M^n$  is  $\eta$ -Einstein manifold. We have shown that if an  $n$ -dimensional  $(LCS)_n$ -manifold  $M^n$  is  $M$ -projective pseudosymmetric then either  $L_{W^*} = (\alpha^2 - \rho)$  or the manifold is Einstein manifold, provided  $(\alpha^2 - \rho) \neq 0$ , in section 4. Section 5 deals with the study of  $\phi$ - $M$ -projective semisymmetric  $(LCS)_n$ -manifold and proved that the manifold is generalized  $\eta$ -Einstein manifold, provided  $(\alpha^2 - \rho) \neq 0$ . In the last section, we have studied generalized  $M$ -projective  $\phi$ -recurrent  $(LCS)_n$ -manifold and gave the relations between the associated 1-forms  $A$  and  $B$ .

## §2. Preliminaries

An  $n$ -dimensional Lorentzian manifold  $M^n$  is a smooth connected para-compact Hausdorff manifold with a Lorentzian metric  $g$  of type  $(0, 2)$  such that for each point  $p \in M$ , the tensor  $g_p : T_p(M^n) \times T_p(M^n) \rightarrow R$  is a non-degenerate inner product of signature  $(-, +, +, \dots, +)$ , where  $T_p(M^n)$  denotes the tangent space of  $M^n$  at  $p$  and  $R$  is the real number space [18,12].

In a Lorentzian manifold  $(M^n, g)$ , a vector field  $P$  defined by

$$g(X, P) = A(X),$$

for any vector field  $X \in \chi(M^n)$ , ( $\chi(M^n)$  being the Lie algebra of vector fields on  $M^n$ ) is said to be a concircular vector field [23] if

$$(\nabla_X A)(Y) = \alpha[g(X, Y) + \omega(X)A(Y)],$$

where  $\alpha$  is a non-zero scalar function,  $A$  is a 1-form and  $\omega$  is a closed 1-form.

Let  $M^n$  be a Lorentzian manifold admitting a unit time like concircular vector field  $\xi$ , called the characteristic vector field of the manifold. Then we have

$$g(\xi, \xi) = -1. \quad (2.1)$$

Since  $\xi$  is a unit concircular vector field, there exists a non-zero 1-form  $\eta$  such that for

$$g(X, \xi) = \eta(X), \quad (2.2)$$

the equation of the following form holds

$$(\nabla_X \eta)(Y) = \alpha[g(X, Y) + \eta(X)\eta(Y)], \quad (\alpha \neq 0) \quad (2.3)$$

for all vector fields  $X$  and  $Y$ . Here  $\nabla$  denotes the operator of covariant differentiation with respect to the Lorentzian metric  $g$  and  $\alpha$  is a non zero scalar function satisfying

$$(\nabla_X \alpha) = (X\alpha) = d\alpha(X) = \rho\eta(X), \quad (2.4)$$

$\rho$  being a certain scalar function given by  $\rho = -(\xi\alpha)$ . If we put

$$\phi X = \frac{1}{\alpha} \nabla_X \xi, \quad (2.5)$$

then from (2.3) and (2.5) we have

$$\phi^2 X = X + \eta(X)\xi, \quad (2.6)$$

$$\eta(\xi) = -1, \quad \phi\xi = 0, \quad \eta(\phi X) = 0, \quad g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y), \quad (2.7)$$

from which it follows that  $\phi$  is a symmetric  $(1, 1)$  tensor, called the structure tensor of the manifold. Thus the Lorentzian manifold  $M$  together with the unit timelike concircular vector field  $\xi$ , its associated 1-form  $\eta$  and  $(1, 1)$  tensor field  $\phi$  is said to be a Lorentzian concircular structure manifold (briefly  $(LCS)_n$ -manifold) [18]. Especially, if we take  $\alpha = 1$ , then we obtain the LP-Sasakian structure of Matsumoto [11].

In a  $(LCS)_n$ -manifold, the following relations hold [18]:

$$\eta(R(X, Y)Z) = (\alpha^2 - \rho)[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)], \quad (2.8)$$

$$R(X, Y)\xi = (\alpha^2 - \rho)[\eta(Y)X - \eta(X)Y], \quad (2.9)$$

$$R(X, \xi)Z = (\alpha^2 - \rho)[\eta(Z)X - g(X, Z)\xi], \quad (2.10)$$

$$R(\xi, X)Y = (\alpha^2 - \rho)[g(X, Y)\xi - \eta(Y)X], \quad (2.11)$$

$$R(\xi, X)\xi = (\alpha^2 - \rho)[X + \eta(X)\xi], \quad (2.12)$$

$$S(X, \xi) = (n-1)(\alpha^2 - \rho)\eta(X), \quad Q\xi = (n-1)(\alpha^2 - \rho)\xi, \quad (2.13)$$

$$(\nabla_X \phi)(Y) = \alpha[g(X, Y)\xi + 2\eta(X)\eta(Y)\xi + \eta(Y)X], \quad (2.14)$$

$$S(\phi X, \phi Y) = S(X, Y) + (n-1)(\alpha^2 - \rho)\eta(X)\eta(Y) \quad (2.15)$$

for all vector fields  $X, Y, Z$  and  $R, S$  respectively denotes the curvature tensor and the Ricci tensor of the manifold.

A  $(LCS)_n$  manifold  $M^n$  is said to be a generalized  $\eta$ -Einstein manifold [30] if the following condition

$$S(X, Y) = \lambda g(X, Y) + \mu\eta(X)\eta(Y) + \nu\Omega(X, Y) \quad (2.16)$$

holds on  $M^n$ . Here  $\lambda, \mu$  and  $\nu$  are smooth functions and  $\Omega(X, Y) = g(\phi X, Y)$ . If  $\nu = 0$  then the manifold reduces to an  $\eta$ -Einstein manifold.

From (1.1), we have

$$\eta(W^*(\xi, Y)Z) = \frac{1}{2(n-1)}S(Y, Z) - \frac{1}{2}g(Y, Z), \quad (2.17)$$

$$\eta(W^*(X, \xi)Z) = -\frac{1}{2(n-1)}S(X, Z) - \frac{3}{2}(\alpha^2 - \rho)g(X, Z), \quad (2.18)$$

$$\eta(W^*(X, Y)\xi) = 0, \quad (2.19)$$

$$W^*(X, Y)\xi = 0, \quad W^*(X, \xi)\xi = 0, \quad W^*(\xi, \xi)Z = 0, \quad (2.20)$$

$$\begin{aligned} W^*(X, \xi, Z, T) = & \frac{1}{2(n-1)}S(X, Z)\eta(T) - \frac{1}{2(n-1)}S(X, T)\eta(Z) \\ & + \frac{1}{2}(\alpha^2 - \rho)g(X, T)\eta(Z) - \frac{1}{2}(\alpha^2 - \rho)g(X, Z)\eta(T), \end{aligned} \quad (2.21)$$

$$W^*(X, \xi, Z, \xi) = -\frac{1}{2(n-1)}S(X, Z) + \frac{1}{2}(\alpha^2 - \rho)g(X, Z), \quad (2.22)$$

$$W^*(X, \xi)Z = \frac{1}{2(n-1)}S(X, Z)\xi - \frac{1}{2}(\alpha^2 - \rho)g(X, Z)\xi, \quad (2.23)$$

$$(\nabla_U S)(X, \xi) = (n-1)\alpha(\alpha^2 - \rho)[g(U, X) + \eta(U)\eta(X)] - \alpha S(X, \phi U). \quad (2.24)$$

### §3. $\phi$ -M-projectively Flat $(LCS)_n$ -Manifold

**Definition 3.1** An  $n$ -dimensional  $(LCS)_n$ -manifold  $(M^n, g)$ ,  $(n > 3)$  is called  $\phi$ -M-projective flat if it satisfies the condition

$$\phi^2 W^*(\phi X, \phi Y)\phi Z = 0, \quad (3.1)$$

for all vector fields  $X, Y, Z$  on the manifold.

**Theorem 3.1** If  $(M^n, g)$  is an  $n$ -dimensional  $\phi$ -M-projective flat  $(LCS)_n$ -manifold, then the manifold  $M^n$  is  $\eta$ -Einstein manifold.

*Proof* Let  $M^n$  be  $\phi$ -M-projective flat. It is easy to define that  $\phi^2(W^*(\phi X, \phi Y)\phi Z) = 0$  holds if and only if

$$g(W^*(\phi X, \phi Y)\phi Z, \phi U) = 0, \quad (3.2)$$

for any vector fields  $X, Y, Z, U \in TM^n$ .

By virtue of (1.1) and (3.2), one can obtain

$$\begin{aligned} g(R(\phi X, \phi Y)\phi Z, \phi U) = & \frac{1}{2(n-1)}[S(\phi Y, \phi Z)g(\phi X, \phi U) - S(\phi X, \phi Z)g(\phi Y, \phi U) \\ & + g(\phi Y, \phi Z)S(\phi X, \phi U) - g(\phi X, \phi Z)S(\phi Y, \phi U)]. \end{aligned} \quad (3.3)$$

Let  $\{e_1, e_2, \dots, e_{n-1}, \xi\}$  be a local orthonormal basis of vector fields in  $M^n$ . By using the fact that  $\{\phi e_1, \phi e_2, \dots, \phi e_{n-1}, \xi\}$  is also a local orthonormal basis, if we put  $X = U = e_i$  in (3.3) and sum up with respect to  $i$ , we get

$$\begin{aligned} \sum_{i=1}^{n-1} g(R(\phi e_i, \phi Y)\phi Z, \phi e_i) &= \frac{1}{2(n-1)} \sum_{i=1}^{n-1} [S(\phi Y, \phi Z)g(\phi e_i, \phi e_i) \\ &\quad - S(\phi e_i, \phi Z)g(\phi Y, \phi e_i) + g(\phi Y, \phi Z)S(\phi e_i, \phi e_i) \\ &\quad - g(\phi e_i, \phi Z)S(\phi Y, \phi e_i)]. \end{aligned} \quad (3.4)$$

It can be easily verify by a straight forward calculation that [1],

$$\sum_{i=1}^{n-1} g(R(\phi e_i, \phi Y)\phi Z, \phi e_i) = S(\phi Y, \phi Z) + g(\phi Y, \phi Z), \quad (3.5)$$

$$\sum_{i=1}^{n-1} S(\phi e_i, \phi e_i) = r - (n-1)(\alpha^2 - \rho), \quad (3.6)$$

$$\sum_{i=1}^{n-1} g(\phi e_i, \phi Z)S(\phi Y, \phi e_i) = S(\phi Y, \phi Z), \quad (3.7)$$

$$\sum_{i=1}^{n-1} g(\phi e_i, \phi e_i) = (n-1) \quad (3.8)$$

and

$$\sum_{i=1}^{n-1} g(\phi e_i, \phi Z)g(\phi Y, \phi e_i) = g(\phi Y, \phi Z). \quad (3.9)$$

By virtue of (3.5) - (3.8), the equation (3.4) becomes

$$S(\phi Y, \phi Z) = \left\{ \frac{r - (n-1)(\alpha^2 - \rho) - 2(n-1)}{n+1} \right\} g(\phi Y, \phi Z). \quad (3.10)$$

On substituting (2.7) and (2.15), (3.10) yields

$$S(Y, Z) = k_1 g(Y, Z) + k_2 \eta(Y)\eta(Z), \quad (3.11)$$

where  $k_1 = \left\{ \frac{r - (n-1)(\alpha^2 - \rho) - 2(n-1)}{n+1} \right\}$  and  $k_2 = \left\{ \frac{r - 2(n-1) - (n-1)(n+1)(\alpha^2 - \rho)}{n+1} \right\}$ . Thus we proved the theorem.  $\square$

#### §4. $M$ -Projective Pseudosymmetric $(LCS)_n$ -Manifold

**Definition 4.1** An  $(LCS)_n$ -manifold  $(M^n, g)$  ( $n > 3$ ) is said to be  $M$ -projective pseudosymmetric if it satisfies

$$(R(X, Y) \cdot W^*)(U, V)E = L_{W^*}((X \wedge Y) \cdot W^*)(U, V)E, \quad (4.1)$$

for any vector fields  $X, Y, U, V, E \in TM^n$ .

**Theorem 4.2** *If an  $n$ -dimensional  $(LCS)_n$ -manifold  $M^n$  is  $M$ -projective pseudosymmetric then either  $L_{W^*} = (\alpha^2 - \rho)$  or the manifold is Einstein manifold, provided  $(\alpha^2 - \rho) \neq 0$ .*

*Proof* Let  $M^n$  be  $M$ -projective pseudosymmetric. Putting  $Y = \xi$  in (4.1), we get

$$\begin{aligned} (R(X, \xi) \cdot W^*)(U, V)E &= L_{W^*}[(X \wedge \xi)W^*(U, V)E - W^*((X \wedge \xi)U, V)E \\ &\quad - W^*(U, (X \wedge \xi)V)E - W^*(U, V)(X \wedge \xi)E]. \end{aligned} \quad (4.2)$$

Now the left hand side of (4.2) reduces to

$$R(X, \xi) \cdot W^*(U, V)E - W^*(R(X, \xi)U, V)E - W^*(U, R(X, \xi)V)E - W^*(U, V)R(X, \xi)E. \quad (4.3)$$

In view of (2.10), (4.3) becomes

$$\begin{aligned} (\alpha^2 - \rho)[W^*(U, V, E, \xi)X - W^*(U, V, E, X)\xi - \eta(U)W^*(X, V)E + g(X, U)W^*(\xi, V)E \\ - \eta(V)W^*(U, X)E + g(X, V)W^*(U, \xi)E - \eta(T)W^*(U, V)X + g(X, E)W^*(U, V)\xi]. \end{aligned} \quad (4.4)$$

Similarly, right hand side of (4.2) reduces to

$$\begin{aligned} L_{W^*}[W^*(U, V, E, \xi)X - W^*(U, V, E, X)\xi - \eta(U)W^*(X, V)E + g(X, U)W^*(\xi, V)E \\ - \eta(V)W^*(U, X)E + g(X, V)W^*(U, \xi)E - \eta(E)W^*(U, V)X + g(X, E)W^*(U, V)\xi]. \end{aligned} \quad (4.5)$$

On replacing the expressions (4.4) and (4.5) in (4.2), we get

$$\begin{aligned} [L_{W^*} - (\alpha^2 - \rho)]\{W^*(U, V, E, \xi)X - W^*(U, V, E, X)\xi - \eta(U)W^*(X, V)E \\ + g(X, U)W^*(\xi, V)E - \eta(V)W^*(U, X)E + g(X, V)W^*(U, \xi)E - \eta(E)W^*(U, V)X \\ + g(X, E)W^*(U, V)\xi\} = 0. \end{aligned} \quad (4.6)$$

Taking  $V = \xi$  and using (2.2) and (2.7) in the above equation, we obtain

$$\begin{aligned} [L_{W^*} - (\alpha^2 - \rho)]\{W^*(U, \xi, E, \xi)X - W^*(U, \xi, E, X)\xi - \eta(U)W^*(X, \xi)E \\ + g(X, U)W^*(\xi, \xi)E + W^*(U, X)E + \eta(X)W^*(U, \xi)E - \eta(E)W^*(U, \xi)X \\ + g(X, E)W^*(U, \xi)\xi\} = 0. \end{aligned} \quad (4.7)$$

On using (2.21) - (2.23), (4.7) gives either  $L_{W^*} = (\alpha^2 - \rho)$  or

$$\begin{aligned} W^*(U, X)E &= \frac{1}{2(n-1)}S(U, E)X + \frac{1}{2(n-1)}S(X, E)\eta(U)\xi \\ &\quad - \frac{1}{2}(\alpha^2 - \rho)g(U, E)X - \frac{1}{2}(\alpha^2 - \rho)g(X, E)\eta(U)\xi. \end{aligned} \quad (4.8)$$

The above equation implies

$$\begin{aligned} W^*(U, X, E, G) &= \frac{1}{2(n-1)}S(U, E)g(X, G) + \frac{1}{2(n-1)}S(X, E)\eta(U)\eta(G) \\ &\quad - \frac{1}{2}(\alpha^2 - \rho)g(U, E)g(X, G) - \frac{1}{2}(\alpha^2 - \rho)g(X, E)\eta(U)\eta(G). \end{aligned} \quad (4.9)$$

Contracting (4.9) gives

$$W^*(e_i, X, E, e_i) = 0. \quad (4.10)$$

Simplifying (4.10), we finally obtain

$$S(X, E) = (n-1)(\alpha^2 - \rho)g(X, E). \quad (4.11)$$

Thus the proof of the theorem is completed.  $\square$

### §5. $\phi$ - $M$ -Projectively Semisymmetric $(LCS)_n$ -Manifold

**Definition 5.1** An  $n$ -dimensional ( $n > 3$ )  $(LCS)_n$ -manifold is said to be  $\phi$ - $M$ -projective semisymmetric if it satisfies the condition

$$W^*(X, Y) \cdot \phi = 0, \quad (5.1)$$

which turns into

$$(W^*(X, Y) \cdot \phi)Z = W^*(X, Y)\phi Z - \phi W^*(X, Y)Z = 0. \quad (5.2)$$

Before we state our theorem we need the following lemma which was proved in [19].

**Lemma 5.2**([19]) If  $M^n$  is an  $(LCS)_n$ -manifold, then for any  $X, Y, Z$  on  $M^n$ , the following relation holds:

$$\begin{aligned} R(X, Y)\phi Z - \phi R(X, Y)Z &= (\alpha^2 - \rho)[\{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\}\xi \\ &\quad + \eta(Z)\{\eta(X)Y - \eta(Y)X\}]. \end{aligned} \quad (5.3)$$

**Theorem 5.3** If an  $n$ -dimensional  $(LCS)_n$ -manifold is  $\phi$ - $M$ -projective semisymmetric then it is a generalized  $\eta$ -Einstein manifold, provided  $(\alpha^2 - \rho) \neq 0$ .

*Proof* By virtue of (1.1), we have

$$\begin{aligned} W^*(X, Y)\phi Z - \phi W^*(X, Y)Z &= R(X, Y)\phi Z - \phi R(X, Y)Z - \frac{1}{2(n-1)}[S(Y, \phi Z)X \\ &\quad - S(X, \phi Z)Y + g(Y, \phi Z)QX - g(X, \phi Z)QY \\ &\quad + S(Y, Z)\phi X - S(X, Z)\phi Y + g(Y, Z)\phi QX - g(X, Z)\phi QY]. \end{aligned} \quad (5.4)$$

On using (2.13) and (5.3) in (5.4), we obtain

$$\begin{aligned}
& (\alpha^2 - \rho)[\{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\}\xi + \eta(Z)\{\eta(X)Y - \eta(Y)X\}] \\
& - \frac{1}{2(n-1)}[S(Y, \phi Z)X - S(X, \phi Z)Y + (n-1)(\alpha^2 - \rho)g(Y, \phi Z)X \\
& - (n-1)(\alpha^2 - \rho)g(X, \phi Z)Y + S(Y, Z)\phi X - S(X, Z)\phi Y \\
& + (n-1)(\alpha^2 - \rho)g(Y, Z)\phi X - (n-1)(\alpha^2 - \rho)g(X, Z)\phi Y] = 0.
\end{aligned} \tag{5.5}$$

Taking inner product of (5.5) with  $T$ , we get

$$\begin{aligned}
& (\alpha^2 - \rho)[\{g(Y, Z)\eta(X) - g(X, Z)\eta(Y)\}\eta(T) + \eta(Z)\{\eta(X)g(Y, T) - \eta(Y)g(X, T)\}] \\
& - \frac{1}{2(n-1)}[S(Y, \phi Z)g(X, T) - S(X, \phi Z)g(Y, T) + (n-1)(\alpha^2 - \rho)g(Y, \phi Z)g(X, T) \\
& - (n-1)(\alpha^2 - \rho)g(X, \phi Z)g(Y, T) + S(Y, Z)g(\phi X, T) - S(X, Z)g(\phi Y, T) \\
& + (n-1)(\alpha^2 - \rho)g(Y, Z)g(\phi X, T) - (n-1)(\alpha^2 - \rho)g(X, Z)g(\phi Y, T)] = 0.
\end{aligned} \tag{5.6}$$

Contracting (5.6) gives

$$\begin{aligned}
S(X, \phi Z) &= \frac{(n-1)(n-2)}{(2-n)}(\alpha^2 - \rho)g(X, \phi Z) + \frac{2(n-1)}{(2-n)}(\alpha^2 - \rho)g(X, Z) \\
&+ \frac{2n(n-1)}{(2-n)}(\alpha^2 - \rho)\eta(X)\eta(Z).
\end{aligned} \tag{5.7}$$

Replacing  $X$  by  $\phi X$  in the above equation, we finally obtain

$$S(X, Z) = \lambda g(X, Z) + \mu \eta(X)\eta(Z) + \nu g(\phi X, Z), \tag{5.8}$$

where  $\lambda = -(n-1)(\alpha^2 - \rho)$ ,  $\mu = -2(n-1)(\alpha^2 - \rho)$  and  $\nu = -\frac{2(n-1)}{(n-2)}$ .

This completes the proof.  $\square$

## §6. Generalized $M$ -Projective $\phi$ -Recurrent $(LCS)_n$ -Manifold

In 2008, Basari and Murathan [2] introduced generalized  $\phi$ -recurrent Kenmotsu manifold. Later, De [8] and Pal [9] studied generalized concircularly recurrent and generalized  $M$ -projectively recurrent Riemannian manifold.

**Definition 6.1** A  $(LCS)_n$ -manifold  $M^n$  ( $n > 3$ ) is said to be generalized  $M$ -projective  $\phi$ -recurrent if it satisfies

$$\phi^2((\nabla_U W^*)(X, Y, Z)) = A(U)W^*(X, Y)Z + B(U)[g(Y, Z)X - g(X, Z)Y], \tag{6.1}$$

where  $A$  and  $B$  are two 1-forms,  $B$  is non-zero and are defined by  $A(U) = g(U, \rho_1)$  and  $B(U) = g(U, \rho_2)$ . Here  $\rho_1$  and  $\rho_2$  are vector fields associated to the 1-forms  $A$  and  $B$  respectively.



**Theorem 6.2** *If the  $(LCS)_n$ -manifold  $M^n$  is generalized  $M$ -projective  $\phi$ -recurrent, then the associated 1-forms  $A$  and  $B$  are related as follows;*

$$\left[\frac{n}{2}(\alpha^2 - \rho) + r\right]A(U) + (n-1)B(U) + \frac{1}{2(n-1)}dr(U) = 0. \quad (6.2)$$

*Proof* Suppose that  $M^n$  is generalized  $M$ -projective  $\phi$ -recurrent  $(LCS)_n$ -manifold. Then, by using (2.6), (6.1) takes the form

$$(\nabla_U W^*)(X, Y)Z + \eta((\nabla_U W^*)(X, Y)Z)\xi = A(U)W^*(X, Y)Z + B(U)[g(Y, Z)X - g(X, Z)Y]. \quad (6.3)$$

From (6.3), it follows that

$$\begin{aligned} & g((\nabla_U W^*)(X, Y, Z), T) + g((\nabla_U W^*)(X, Y, Z), \xi)g(T, \xi) \\ & - \frac{1}{2(n-1)}[(\nabla_U S)(Y, Z)g(X, T) - (\nabla_U S)(X, Z)g(Y, T) + g(Y, Z)(\nabla_U S)(X, T) \\ & - g(X, Z)(\nabla_U S)(Y, T)] - \frac{1}{2(n-1)}[(\nabla_U S)(Y, Z)\eta(X) - (\nabla_U S)(X, Z)\eta(Y) \\ & + g(Y, Z)(\nabla_U S)(X, \xi) - g(X, Z)(\nabla_U S)(Y, \xi)]\eta(T) = A(U)[g(R(X, Y)Z, T) \\ & - \frac{1}{2(n-1)}\{S(Y, Z)g(X, T) - S(X, Z)g(Y, T) + g(Y, Z)S(X, T) - g(X, Z)S(Y, T)\}] \\ & + B(U)[g(Y, Z)g(X, T) - g(X, Z)g(Y, T)]. \end{aligned} \quad (6.4)$$

On contraction, the above equation yields

$$\begin{aligned} & (\nabla_U S)(Y, Z) + \eta((\nabla_U R)(\xi, Y, Z)) - \frac{1}{2(n-1)}[(n-2)(\nabla_U S)(Y, Z) \\ & + dr(U)g(Y, Z)] - \frac{1}{2(n-1)}[-(\nabla_U S)(Y, Z) - (\nabla_U S)(Z, \xi)\eta(Y) + g(Y, Z)(\nabla_U S)(\xi, \xi) \\ & - (\nabla_U S)(Y, \xi)\eta(Z)] = A(U)[S(Y, Z) - \frac{1}{2(n-1)}\{(n-2)S(Y, Z) + rg(Y, Z)\}] \\ & + (n-1)B(U)g(Y, Z). \end{aligned} \quad (6.5)$$

In (6.5), setting  $Z = \xi$  and then using (2.2), (2.3), (2.7), (2.12) and (2.13) one can get

$$\begin{aligned} & (\nabla_U S)(Y, \xi)\left[1 - \frac{n-2}{2(n-1)}\right] - \frac{dr(U)}{2(n-1)}\eta(U) = A(U)[S(Y, \xi) \\ & - \frac{1}{2(n-1)}\{(n-2)S(Y, \xi) + r\eta(Y)\}] + (n-1)B(U)\eta(Y). \end{aligned} \quad (6.6)$$

Now, taking  $Y = \xi$  in (6.6) and using (2.2), (2.7) and (2.24), we finally obtain (6.2).  $\square$

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